

# Integrals

To build up the electric or magnetic field of a complicated system, we will integrate over the source charges or currents. This involves integrating over curves, surfaces, and volumes.

## Line Integrals

$$\int_{\text{curve}} f \, dl$$

## Surface Integrals

$$\int_{\text{surface}} f \, da$$

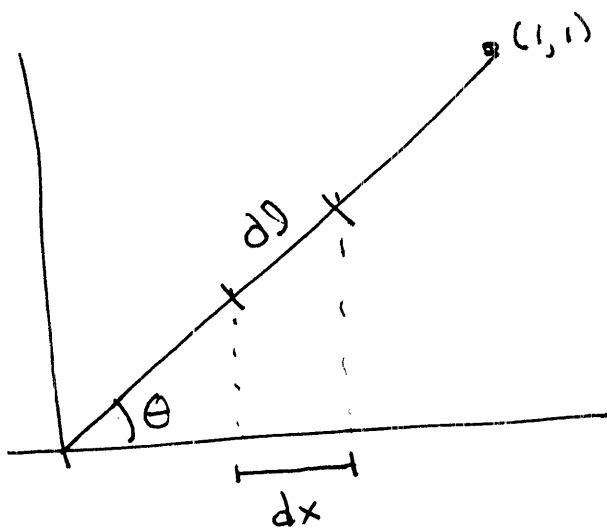
## Volume Integrals

$$\int_{\text{volume}} f \, d\tau$$

To evaluate any of these, imagine dividing the object into small pieces.

(8)

Ex Compute  $\int dl$  along the line from  $(0,0)$  to  $(1,1)$ .  
Note, this is obviously just the length of the line  $\sqrt{2}$ .



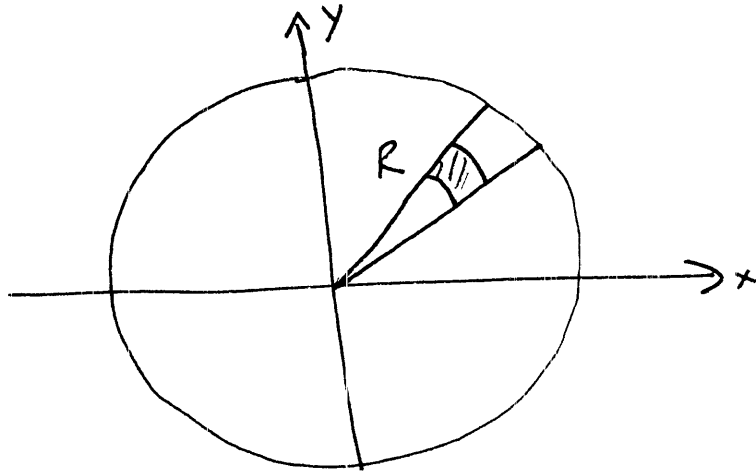
Sln We don't integrate over the line directly, but over one of the coordinate lines, so we have to express  $dl$  in terms of  $dx$ . Evidently, from the figure

$$dl = dx / \cos \theta = \sqrt{2} dx$$

$$\int_{\text{line}} dl = \int_0^1 \sqrt{2} dx = \sqrt{2} \quad \checkmark$$

(9)

Ex Compute area of a circle of radius  $R$



$$\text{Area} = \int_{\text{circle}} da$$

We can evaluate this in any coordinate system. It is somewhat complicated in cartesian where  $da = dx dy$ . Try cylindrical. A small area element is drawn above.

$$da = (dr)(r d\theta)$$

$$\text{Area} = \int_{\text{circle}} da = \int_0^R dr \int_0^{2\pi} r d\theta$$

$$= \int_0^R 2\pi r dr = \pi R^2$$

# Integral Theorems

We will convert VP.II into this class using a number of integral theorems.

## Gradient

The total derivative of a function can be written

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$

The integral of  $df$  is

$$\int_{\vec{r}_a}^{\vec{r}_b} df = f(\vec{r}_b) - f(\vec{r}_a)$$

In Cartesian coordinates, the path element is  $d\vec{\ell} = \hat{x} dx + \hat{y} dy + \hat{z} dz$ , the infinitesimal displacement.

therefore

$$df = \nabla f \cdot d\vec{\ell}$$

The line integral, where  $d\vec{l}$  is an element of the line of the gradient is

$$I \equiv \int_{\vec{r}_a \rightarrow \vec{r}_b} \nabla f \cdot d\vec{l} = \int_{\vec{r}_a}^{\vec{r}_b} df = f(\vec{r}_b) - f(\vec{r}_a)$$

•  $\Rightarrow$   $I$  is independent of the path. It depends only on the end points.

$\Rightarrow$  If the path is closed  $\vec{r}_a = \vec{r}_b$ ,  $I = 0$ .

Divergence Thm

$$\int_{\text{volume}} (\nabla \cdot \vec{A}) d\tau = \oint_{\text{surface}} \vec{A} \cdot d\vec{a}$$

- surface = closed surface surrounding volume
- $d\vec{a} = \hat{n} da$  where  $\hat{n}$  is outward surface normal; a vector  $\perp$  to the surface.

Flux The flux or flow of the field  $\vec{A}$  out of a closed surface  $S$  is defined as

$$\Phi = \int_S \vec{A} \cdot d\vec{a}$$

So the integral of the divergence of the field over a volume equals the flow out of the volume.

---

Stoke's Thm The integral of the field  $\vec{A}$  around a closed curve  $C$  is equal to the total curl of the field over the surface  $S$  bounded by  $C$ .

$$\int_C \vec{A} \cdot d\vec{x} = \int_S (\nabla \times \vec{A}) \cdot d\vec{a}$$

⇒ Chose  $\hat{n}$  for  $S$  by curling fingers in direction of  $C$ , thumb points in  $\hat{n}$  direction.

There are many other integral formulas

$$\int_{\text{Volume}} (\nabla f) d\tau = \oint_S f d\vec{a}$$

$$\int_S \nabla f \times d\vec{a} = - \oint_C f d\vec{l}$$

$$\int_V (\nabla \times \vec{A}) d\tau = - \oint_S \vec{A} \times d\vec{a}$$

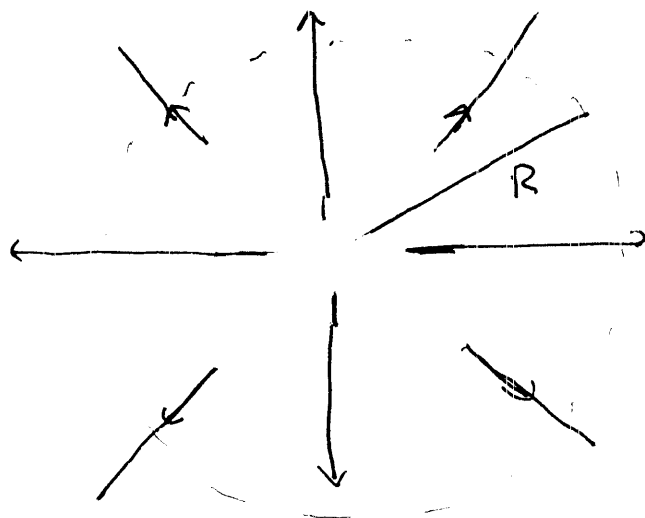
$$\int_S (d\vec{a} \times \nabla) \times \vec{A} = - \oint_C \vec{A} \times d\vec{l} \quad (\text{Stokes 2})$$

$$\int_V (f \nabla^2 g + \nabla f \cdot \nabla g) d\tau = \oint_S (f \nabla g) \cdot d\vec{a} \quad (\text{Green 1})$$

$$\int_V (f \nabla^2 g - g \nabla^2 f) d\tau = \oint_S (f \nabla g - g \nabla f) \cdot d\vec{a}$$

(5)

Ex Consider the field  $\vec{A} = \gamma \hat{r}$ . The field points outward from the origin. It grows stronger as you move away from the origin.



The flux out of a sphere of radius  $R$  is

$$\Phi = \oint_{\text{surface}} \vec{A} \cdot d\vec{a}$$

$$d\vec{a} = \hat{r} r \sin\theta d\phi r d\theta = \hat{r} R^2 \sin\theta d\phi d\theta$$

$$\Phi = \oint (\gamma \hat{r}) \cdot \hat{r} R^2 d\phi d\theta \sin\theta$$

$$\vec{r} = r \hat{r} \quad \vec{r} \cdot \hat{r} = r = R$$



(6)

$$\Phi = \gamma R^3 \int_0^{2\pi} d\phi \int_0^{\pi} d\theta \sin\theta$$

$$\underbrace{\int_0^{\pi} d\theta \sin\theta}_{-\cos\theta \Big|_0^{\pi}}$$

$$2$$

$$\Phi = 2\gamma R^3 \int_0^{2\pi} d\phi$$

$$= 4\pi R^3 \gamma = (4\pi R^2)(\gamma R)$$

$$= \text{surface area} \cdot A$$

~~$\nabla \cdot \vec{A}$~~  Now check divergence

$$\vec{A} = \underbrace{\gamma r}_{A_r} \hat{r} + 0 \hat{\theta} + 0 \hat{\phi}$$

Front Cover  $\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r)$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} (\gamma r^3)$$

$$= \frac{3\gamma r^2}{r^2} = 3\gamma$$

$$\int_{\text{volume}} \nabla \cdot \vec{A} \, d\tau = \int_{\text{volume}} 3\gamma \, d\tau$$

$$= 3\gamma \int_{\text{volume}} d\tau = 3\gamma \cdot \frac{4}{3} \pi R^3$$

$$= 4\pi R^3 \gamma \quad \checkmark$$

Ex Investigate Stoke's Thm Pick a field that is purely rotational

$$\vec{A} = \gamma \hat{\phi}$$

and apply Stoke's Thm for a circular surface of radius R.  $d\vec{x} = R d\phi \hat{\phi}$

$$\oint_C \vec{A} \cdot d\vec{x} = \oint_C \vec{A} \cdot (R \hat{\phi} d\phi)$$

$$= \oint_C \gamma \hat{\phi} \cdot (R \hat{\phi} d\phi) = R\gamma \oint_C d\phi$$

$$= 2\pi R\gamma$$

Compute Curl (cylindrical)

$$A_s = 0, A_\phi = \gamma, A_z = 0$$

$$\nabla \times \vec{A} = -\frac{\partial A_\phi}{\partial z} \hat{s} + \frac{1}{s} \left[ \frac{\partial}{\partial s} (s A_\phi) \right] \hat{z}$$

$$= \frac{1}{s} \frac{\partial}{\partial s} (s \gamma) \hat{z} = \frac{\gamma}{s} \hat{z}$$

Compute

$$d\vec{a} = s d\phi ds \hat{z}$$

$$\int_{\text{circle}} \nabla \times \vec{A} \cdot d\vec{a} = \int_0^{2\pi} d\phi \int_0^R s ds \left( \frac{\gamma}{s} \hat{z} \cdot \hat{z} \right)$$

$$= \gamma \int_0^{2\pi} d\phi \int_0^R ds$$

$$= 2\pi R \gamma$$

