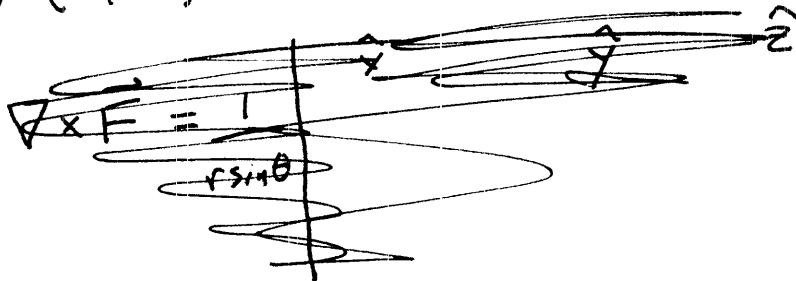


## Central Forces

Central Force -  $\vec{F} = f(r) \hat{r}$  - Force always directed toward or away from some center, chosen to be the origin.

What is conserved for a central force?

Energy (Yes) -



$$\vec{F} = F_r \hat{r} + F_\theta \hat{\theta} + F_\phi \hat{\phi}$$

" " " "

f(r) 0 0

Using Griffith's formula for the curl in spherical coordinates.

$$\nabla \times \vec{F} = \frac{1}{r} \frac{1}{\sin \theta} \frac{\partial F_r}{\partial \theta} \hat{\theta} + \frac{1}{r} \frac{\partial F_r}{\partial \theta} \hat{\phi}$$

keeping only terms with  $F_r$ .

(2)

so  $\nabla \times \vec{F} = 0 \Rightarrow$  Force is conservative

$$\vec{F} = -\nabla V$$

Since  $f$  depends only on  $r$ ,

$$f(r) = -\frac{dV}{dr}$$

$$V = - \int f(r) dr$$

Ex The potential energy of the gravitational

$$\text{force, } f(r) = -\frac{mMg}{r^2}$$

$$V(r) = - \int \frac{mMg}{r^2} dr$$

$$= -\frac{mMg}{r} + C$$

$$V(\infty) = 0 \\ \Rightarrow C = 0$$

$$V(r) = -\frac{mMg}{r}$$

(3)

Momentum not conserved  $\Rightarrow$  Object exerting central force not in system. Momentum exchanged with external object.

Dfn Angular Momentum ( $\vec{L}$ ) - The angular momentum about the origin is

$$\vec{L} = \vec{r} \times \vec{p}$$

For a central force,

$$\begin{aligned}\frac{d\vec{L}}{dt} &= \frac{d}{dt}(\vec{r} \times \vec{p}) = \frac{d\vec{r}}{dt} \times \vec{p} + \vec{r} \times \frac{d\vec{p}}{dt} \\ &= \vec{v} \times \vec{p} + \vec{r} \times \vec{F}\end{aligned}$$

$$\text{But } \vec{v} \times \vec{p} = \vec{v} \times m\vec{v} = m\vec{v} \times \vec{v} = 0$$

$$\text{and } \vec{r} \times \vec{F} = \vec{r} \times f(r)\hat{r} = r f(r) \hat{r} \times \hat{r} = 0$$

so  $\frac{d\vec{L}}{dt} = 0 \Rightarrow$  Angular momentum is conserved.

(4)

Since  $\vec{L}$  is constant, and  $\vec{L} = \vec{r} \times m\vec{v}$ ,  
 the motion occurs in the plane defined by  
 $\vec{r}$  and  $\vec{v}$ . The plane is  $\perp$  to  $\vec{L}$ .

$\Rightarrow$  Motion is two-dimensional, let motion  
 occur in x-y plane with  $\vec{L}$  in  $\hat{z}$   
 direction.

The text defines  $\vartheta = \frac{|\vec{L}|}{m}$  which is  
 also a constant.

Work out  $\vec{L}$  in plane-polar coordinates. From  
 Kinematics sheet.

$$\vec{r} = r\hat{r}$$

$$\vec{v} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\vec{L} = \vec{r} \times \vec{p} = m\vec{r} \times \vec{v} = m \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \dot{r} & 0 & 0 \\ \dot{r} & r\dot{\theta} & 0 \end{vmatrix}$$

$$= mr^2\dot{\theta}\hat{z}$$

(5)

$$\frac{|\vec{r}|}{m} = r^2 \dot{\theta} \equiv \lambda \quad \text{constant}$$

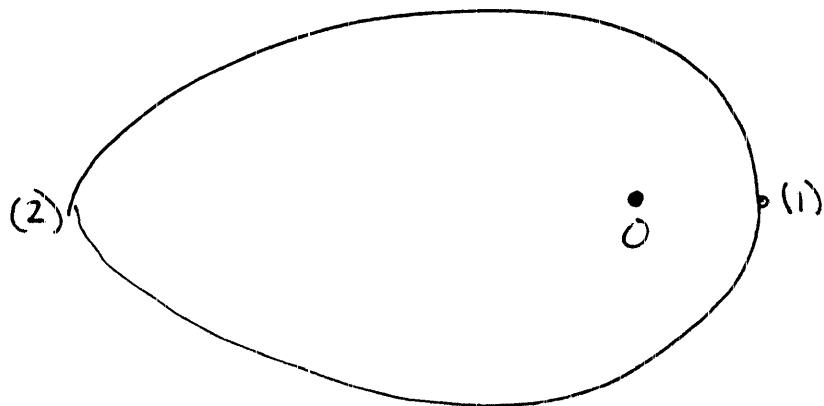
What do we want to know?

I Trajectory  $r(t), \theta(t)$

II Orbit - Shape of the trajectory  $r(\theta)$ .

III Extreme points - Points where  
 $\dot{r}=0$  (no moving to center) or  
 $\dot{\theta}=0$ , but since  $\lambda = r^2 \dot{\theta}$  there are  
none of these.

For a gravitational central force, the  
orbit is an ellipse



(6)

At point (1) and (2)  $\dot{r}=0$ , and  $\vec{F} \perp \vec{v}$

$$\text{so } L = mr\dot{\theta} = m\dot{\theta} \quad \text{and} \quad r\dot{\theta} = \ell.$$


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So what can we do with this?

Ex Suppose a particle in a central force has a spiral orbit given by  $r=\theta$ . Find the trajectory.

$$L = r^2\dot{\theta} = \text{constant}$$

$$= \theta^2\dot{\theta} = \theta^2 \frac{d\theta}{dt}$$

$$\int_0^t dt = \int_0^\theta \theta^2 d\theta \quad \text{letting } \theta=0 \text{ at } t=0.$$

$$\int dt = \frac{\theta^3}{3}$$

$$\theta(t) = (3\int dt)^{1/3}$$

$$r(t) = \theta(t) = (3\int dt)^{1/3}$$

(7)

## Conservation of Energy.

$$E = \text{constant} = \frac{1}{2} mv^2 + V(r)$$

$$v^2 = \vec{v} \cdot \vec{v} = \dot{r}^2 + r^2 \dot{\theta}^2$$

$$\frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + V(r) = E$$

Because it works, try  $v \equiv \frac{1}{r}$ .

$$r = \frac{1}{v}$$

$$\dot{r} = -\frac{1}{v^2} \dot{v} = -\frac{1}{v^2} \frac{dv}{dt}$$

$$= -\frac{1}{v^2} \frac{du}{d\theta} \frac{d\theta}{dt} = -\frac{\dot{\theta}}{v^2} \frac{du}{d\theta}$$

So

$$E = \frac{1}{2} m \frac{\dot{\theta}^2}{v^4} \left( \frac{dv}{d\theta} \right)^2 + \frac{1}{2} m \frac{\dot{v}^2}{v^2} + V(v^{-1})$$

Since  $\vec{L}$  conserved,  ~~$\vec{r} \times \vec{p}$~~   $r^2 \dot{\theta} = \lambda$

$$\dot{\theta} = \lambda v^2$$

(8)

## Energy Equation of Orbit

$$E = \frac{1}{2} m J^2 \left( \left( \frac{du}{d\theta} \right)^2 + u^2 \right) + V(u^{-1})$$

E<sub>x</sub> What central force would produce spiral trajectory  $r = a \theta$  (a constant)?

$$\frac{1}{u} = a \theta$$

$$u = \frac{1}{a} \frac{1}{\theta}$$

$$\frac{du}{d\theta} = -\frac{1}{a} \frac{1}{\theta^2} = -a \frac{1}{a^2 \theta^2} = -au^2$$

$$E = \frac{1}{2} m J^2 \left( a^2 u^4 + u^2 \right) + V(u^{-1})$$

$$V(r) = E - \frac{1}{2} m J^2 \left( \frac{a^2}{r^4} + \frac{1}{r^2} \right)$$

$$f(r) = -\frac{dV}{dr} = \frac{1}{2} m J^2 \left( -\frac{4a^2}{r^5} - \frac{2}{r^3} \right)$$

$$= -\frac{1}{2} m \frac{J^2}{r^3} \left( 2 + \frac{4a^2}{r^2} \right)$$

①

# Orbital Equations of Motion

EOM

$$\vec{F} = m\vec{a} = f(r)\hat{r}$$

$$= m[r\ddot{r} - r\dot{\theta}^2] \hat{r} + m[2r\dot{r}\dot{\theta} + r\ddot{\theta}] \hat{\theta}$$

—————  
Kinematics sheet

Component EOM

$$\hat{r}: \quad f(r) = m\ddot{r} - r\dot{r}\dot{\theta}^2$$

$$\hat{\theta}: \quad \dot{\theta} = 2\dot{r}\dot{\theta} + r\ddot{\theta}$$

Use conservation of momentum

$$l = r^2\dot{\theta} = \text{constant}$$

$$\begin{aligned} \frac{dl}{dt} &= r^2\ddot{\theta} + 2rr\dot{r}\dot{\theta} \\ &= r(2\dot{r}\dot{\theta} + r\ddot{\theta}) \end{aligned}$$

So if angular momentum is conserved,  $\hat{\theta}$  equation is taken care of.

(2)

$$\underline{\text{Solve}} \quad f(r) = mr\dot{r} - r\dot{\theta}^2$$

$$\text{Again try } r = \frac{1}{v}$$

$$\dot{r} = -\frac{1}{v^2} \frac{du}{dt} = -\frac{1}{v^2} \frac{du}{d\theta} \frac{d\theta}{dt}$$

$$= -\frac{\dot{\theta}}{v^2} \frac{du}{d\theta}$$

$$\text{but } l = r^2 \dot{\theta} = \frac{\dot{\theta}}{v^2}$$

$$\dot{r} = -l \frac{du}{d\theta}$$

$$\ddot{r} = -l \frac{d}{dt} \frac{du}{d\theta} = -l \frac{d}{d\theta} \frac{du}{dt}$$

$$= -l \left( \frac{d}{d\theta} \frac{du}{d\theta} \right) \frac{d\theta}{dt}$$

$$= -l \dot{\theta} \frac{d^2 u}{d\theta^2} = -l^2 v^2 \frac{d^2 u}{d\theta^2}$$

(3)

$$f(v^{-1}) = m \left[ -\ell^2 v^2 \frac{d^2 v}{d\theta^2} - \frac{1}{v} (\ell^2 v^4) \right]$$

$$= -m \ell^2 v^2 \left[ \frac{d^2 v}{d\theta^2} + v \right]$$

### Differential Equation of Orbit

$$\frac{d^2 v}{d\theta^2} + v = \frac{f(v^{-1})}{-m \ell^2 v^2}$$

Ex Same problem again, suppose  $r = a \theta$

$$\frac{1}{v} = a \theta \quad v = \frac{1}{a} \frac{1}{\theta}$$

$$\frac{dv}{d\theta} = -\frac{1}{a\theta^2} \quad \frac{d^2 v}{d\theta^2} = \frac{2}{a\theta^3}$$

$$= -av^2 \quad = 2a^2 v^3$$

$$-\frac{f(v^{-1})}{m \ell^2 v^2} = \frac{d^2 v}{d\theta^2} + v = 2a^2 v^3 + v$$

$$f(r) = -\frac{m \ell^2}{r^2} \left( \frac{2a^2}{r^3} + \frac{1}{r} \right)$$

which is what we got before.