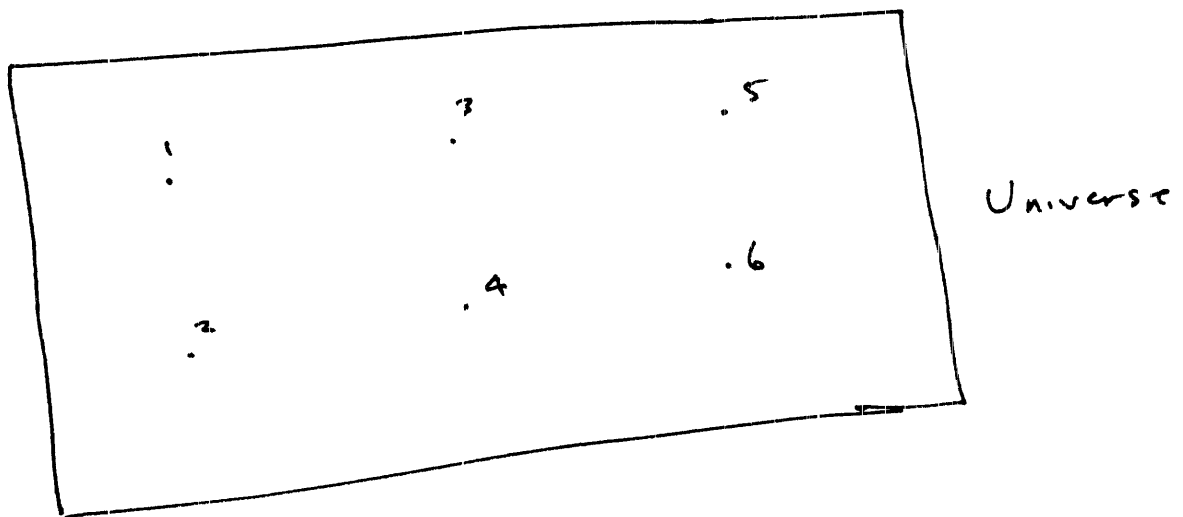


Variable Mass (Rocket) Problems

We have been considering systems where the N particles in the system are constant.

We will now consider the case where the number of particles in the system can change.



If the above is a gas of six particles, then the total momentum is about zero.

$$\begin{array}{l} \vec{P}_{cm} = 0 \\ \text{System} \end{array} \qquad \begin{array}{l} \vec{P}_{env} = 0 \\ \text{Environment} \end{array}$$

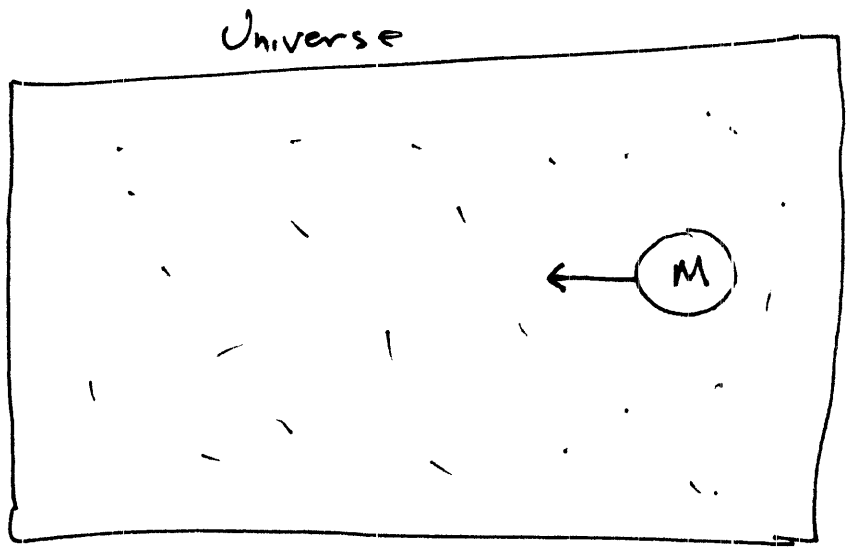
Now suppose in the time Δt we redefine the system to only include particles traveling to the right.

The total momentum of the universe is still zero $\vec{P}_{cm} + \vec{P}_{env} = 0$, but both \vec{P}_{cm} and \vec{P}_{env} are non-zero.

Redefining the system changed the momentum of the system and therefore produced a "force" on the center of mass.

$$\vec{F}_{cm} = \frac{\Delta \vec{P}}{\Delta t} = \frac{\vec{P}_{cm}}{\Delta t} = -\frac{\vec{P}_{env}}{\Delta t}$$

Let's try a different example, a rock moving through a stationary sticky cloud of ~~rock~~ dust.



If the velocity of the rock at $t=0$ is v_0 , then the total momentum of the universe is Mv_0 , which must be conserved.

Let's assume the rate dust is accumulated is proportional to the speed of the system,

$$\alpha v = \frac{dm}{dt}$$

Let's separate the momentum of the universe into the momentum of the dust/rock system \vec{P}_{sys} and other stuff, the environment, \vec{P}_{env} .

$$\vec{P}_{universe} = \vec{P}_{sys} + \vec{P}_{env}$$

$$\frac{d\vec{P}_{uni}}{dt} = 0 = \frac{d\vec{P}_{sys}}{dt} + \frac{d\vec{P}_{env}}{dt}$$

$$\vec{P}_{sys} = M_{sys} \vec{V}_{sys}$$

$$\vec{P}_{env} = M_{env} \vec{V}_{env}$$

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$$0 = M_{env} \frac{d\vec{v}_{env}}{dt} + \vec{v}_{env} \frac{dM_{env}}{dt} \\ + M_{sys} \frac{d\vec{v}_{sys}}{dt} + \vec{v}_{sys} \frac{dM_{sys}}{dt}$$

Ignore external forces on the environment, $\dot{\vec{v}}_{env} = 0$.

$$M_{sys} \frac{d\vec{v}_{sys}}{dt} = -\vec{v}_{env} \frac{dM_{env}}{dt} - \vec{v}_{sys} \frac{dM_{sys}}{dt}$$

For our rock/dust system $\vec{v}_{env} = 0$, and let

$$M_{sys} \equiv m, \quad \vec{v}_{sys} \equiv v$$

$$m \frac{dv}{dt} = -v \frac{dm}{dt}$$

With our assumption that $\frac{dm}{dt} = \alpha v$ this becomes

$$m \frac{dv}{dt} = -\alpha v^2$$

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The dust attaching to the system exerts a quadratic drag force. If the initial velocity at $t=0$ is v_0 .

$$\int_{v_0}^v \frac{dv}{v^2} = - \int_0^t \frac{\alpha}{m} dt$$

$$-\frac{1}{v} \Big|_{v_0}^v = -\frac{\alpha}{m} t$$

$$\frac{1}{v_0} - \frac{1}{v} = -\frac{\alpha}{m} t$$

$$\frac{1}{v} = \frac{1}{v_0} + \frac{\alpha t}{m} = \frac{m + \alpha t v_0}{v_0 m}$$

$$v = \frac{v_0 m}{m + \alpha t v_0} = v_0 \left(\frac{1}{1 + \alpha t v_0 / m} \right)$$

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What happens if the dust is moving at the same rate as the rock, but still accreting at the same rate?

$$\vec{v}_{sys} = \vec{v}_{env}$$

$$m \frac{d\vec{v}_{sys}}{dt} = -\vec{v}_{sys} \left(\frac{dM_{env}}{dt} + \frac{dM_{sys}}{dt} \right)$$

= 0, if mass conserved

⇒ No force

⇒ Force depends on relative velocity of system and the mass added to the system.

In general, with $m = M_{sys}$

$$\frac{dm}{dt} = \frac{dM_{sys}}{dt} = -\frac{dM_{env}}{dt}$$

$$m \frac{d\vec{v}_{sys}}{dt} = -\vec{v}_{env} \left(-\frac{dm}{dt} \right) - \vec{v}_{sys} \frac{dm}{dt}$$

$$m(t) \frac{d\vec{v}_{sys}}{dt} = \left(\vec{v}_{env} - \vec{v}_{sys} \right) \frac{dm}{dt}$$

Let $\vec{v}_{rel} = \vec{v}_{env} - \vec{v}_{sys} =$ relative velocity

$$m(t) \frac{d\vec{v}_{sys}}{dt} = \vec{v}_{rel} \frac{dm}{dt}$$

Naturally, we can also exert an external force on the object. So in general, for a system of changing mass.

$$m(t) \frac{d\vec{v}_{sys}}{dt} = \vec{v}_{rel} \frac{dm}{dt} + \vec{F}_{ext}$$

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Ex Consider a rocket, where the rocket is propelled with a constant exhaust velocity (relative to the rocket) of v_{rel} . The mass of the rocket changes as $m(t) = m_0 - \alpha t$ where m_0 is the initial mass. The rocket runs out of fuel at $m(\tau_b) = m_b$ where m_b is the burn-out mass and τ_b is the time to burn out. How fast is the rocket going at τ_b ?

$$m(t) \frac{dv}{dt} = -v_{rel} \frac{dm}{dt}$$

exhaust gas ejected in - direction to direction of motion.

$$\frac{dm}{dt} = -\alpha$$

$$m(t) \frac{dv}{dt} = \alpha v_{rel}$$

$$dv = \frac{\alpha v_{rel}}{m(t)} dt$$

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$$\int_0^{v_b} dv = \int_0^{T_b} \frac{\alpha v_{rel}}{m_0 - \alpha t} dt$$

$$v_b = -\frac{1}{\alpha} \alpha v_{rel} \ln(m_0 - \alpha t) \Big|_0^{T_b}$$

$$= \ln\left(\frac{m_0}{m_0 - \alpha T_b}\right) v_{rel}$$

$$m_0 - \alpha T_b = m_f$$

$$v_b = v_{rel} \ln\left(\frac{m_0}{m_f}\right)$$

Ex

I had to do this every year, because my kid wanted a pinata for her birthday. Consider throwing a baseball of mass m_0 with a rope of mass λ per unit length straight up in the air. How high does it go if initial velocity is v_0 ?

Let the environment contain the part of the rope still on the ground. $v_{env} = 0$.

$$v_{rel} = \cancel{v_{sys} - v_{env}} \\ = v_{env} - v_{sys} = -v_{sys}$$

If the ball is thrown from a height h_0 , the mass of the system is

$$m(y) = m_0 + \lambda y$$

$$m(y) \frac{dv_{sys}}{dt} = -v_{sys} \frac{dm}{dt} - mg$$

$$m(y) \ddot{y} = -\dot{y}(\lambda \dot{y}) - mg$$

$$(m_0 + \lambda y) \frac{dy}{dy} \frac{dy}{dt} = -\lambda v^2 - mg$$

$$(m_0 + \lambda y) v \frac{dv}{dt} = -\lambda v^2 - mg$$

and we're stuck.